

# Importance of modeling in the process of development of biomedical implants

ENABLINGTECH

LA SURDORI

Philippe Maxy

Principal Scientist, Technical Fellow





Importance of modeling in the process of development of biomedical implants

# INTRODUCTION







#### Fully Validated Geometrical & Mechanical Model



INTEGRATED SPINE SOLUTIONS

SERVICES & SUPPORT

15.00 (Bap) 10.00

15.0

6 9 10.00

Rotatio 50

#### Aredtronic

# Why use FEA?

- Fundamental Research
  - For a Better Knowledge
- From Fundamental to Applied Research
  For a Better Concept
- Development & Design Optimization
  For a Better Design
- Malfunction Analysis & Understanding
  For a Better Prevention of Risks





NABUNG TECHNOL





Importance of modeling in the process of development of biomedical implants

# **FUNDAMENTAL RESEARCH**



#### Medtronic

#### **Fundamental Research**

**Exemple**: Burst-Fracture Instrumentations

A fully validated 3D FEA model of the spine can be a powerfull tool to obtain the mechanical environment of the fixation device (forces & moments distribution along the pedicle screws, etc.)

A Burst Fracture can be used as a clinical case to compare different posterior fixation techniques.

Optimize implants with the knowledge of forces and moments that are acting on the device.









THERPICS

### **Fundamental Research**

 Increase rotation of the injured segment, mainly in torsion





THERE

## **Fundamental Research**

- Increase rotation of the injured segment, mainly in torsion
- No significant difference in mobilities between the 4 devices









#### **Fundamental Research**



 High stresses were found in the pedicle screw for the Short Device



ENABUNG TECHNOLOGIES



#### **Fundamental Research**



• High stresses were found in the pedicle screw for the Short Device

ENABUNG TECHNOLOGIES

 The infralaminar hook unloaded the lower pedicle screw and did not change the stress distribution in the upper pedicle screw





### **Fundamental Research**



• High stresses were found in the pedicle screw for the Short Device

ENABLING TECHNOLOGIES

- The infralaminar hook unloaded the lower pedicle screw and did not change the stress distribution in the upper pedicle screw
- The bone graft also yielded a decrease of stresses both in lower and upper screws





INTEGRATED

#### **Fundamental Research**

•

#### 18 16 Pedicle stresses (Mpa) 14 in Flexion 12 10 8 6 4 2 0 -L2 L4 Short D Short D + ILH Short D + ISA Long D

SERVICES & SUPPORT

- not change the stress distribution in the upper pedicle screw
   The bone graft also yielded a decrease of stresses both in
  - lower and upper screws
  - Pedicle stresses disappeared with the long device

High stresses were found in the

The infralaminar hook unloaded

the lower pedicle screw and did

pedicle screw for the Short Device





INTEGRATED

### **Fundamental Research**

#### 18 16 Pedicle stresses (Mpa) 14 in Flexion 12 10 8 6 4 2 0 -L3 L2 L4 Short D Short D + ILH Short D + ISA Long D

SERVICES & SUPPORT

• High stresses were found in the pedicle screw for the Short Device

ENABLING TECHNOLOGI

- The infralaminar hook unloaded the lower pedicle screw and did not change the stress distribution in the upper pedicle screw
- The bone graft also yielded a decrease of stresses both in lower and upper screws
- Pedicle stresses disappeared with the long device



#### Medtronic

### **Fundamental Research**

- Spinal Finite Element model allows us to analyze not only the segmental mobility, but also the stress distribution in the vertebral segment for various constructs.
- It emphasizes the role of hooks or of bone graft in protecting the pedicle screws from excessive stresses.
- Such a Finite Element model of the vertebral spine appears to be a powerful simulation tool which yields new useful information to complement experimental data and can help in answering most conceptual design questions.





ENABLING TECHNOLOGIES

Importance of modeling in the process of development of biomedical implants

# FROM FUNDAMENTAL TO APPLIED RESEARCH





# **From Fundamental to Applied Research**

ENABLING TECHNOLOGIES

- Short Devices:
  - Stress peak in pedicle area

Bending moment in the left upper screw







THEMPS

# **From Fundamental to Applied Research**











THERME

### **From Fundamental to Applied Research**

- Long Device
  - Lowering and moving of stress peak from pedicle area to screw head junction

Bending moment in the left upper screw







THERE

### **From Fundamental to Applied Research**

- Long Device
  - Lowering and moving of stress peak from pedicle area to screw head junction
- Intersomatic arthrodesis:
  - Intermediate solution between short device and long device in terms of implant forces









Importance of modeling in the process of development of biomedical implants

# DEVELOPMENT & DESIGN OPTIMIZATION







![](_page_23_Figure_0.jpeg)

![](_page_24_Figure_0.jpeg)

![](_page_24_Picture_1.jpeg)

## Two holes on Valley: Seems better !

![](_page_24_Figure_3.jpeg)

ENABLING TECHNOLOGIES

![](_page_25_Picture_0.jpeg)

•

![](_page_25_Figure_1.jpeg)

![](_page_25_Figure_2.jpeg)

**ASTM F-1798** 

26

ENNBUNG TECHNOLOGIES

#### Medtronic

## **Development & Design Optimization**

#### Axial pull-out following ASTM-F543 standard

- Anterior part of vertebral body rigidly clamped
- Axial ramped load on the screw until total pull-out ٠
- Measurement of screw displacement and resulting ٠ forces

![](_page_26_Picture_6.jpeg)

AAA

## **Development & Design Optimization**

#### Caudo-cranial toggling

- Anterior part of vertebral body rigidly clamped
- Caudo-cranial sinusoidal load on the screw head
- Measurement of screw displacement and resulting forces
- Force to failure and fracture pattern was analyzed.

![](_page_27_Picture_7.jpeg)

SERVICES & SUPPORT

INTEGRATED SPINE SOLUTIONS

![](_page_27_Picture_9.jpeg)

![](_page_28_Picture_0.jpeg)

ENNBLING TECHNOLOGIES

Importance of modeling in the process of development of biomedical implants

# VALIDATION

![](_page_28_Picture_4.jpeg)

![](_page_29_Picture_0.jpeg)

SERVICES & SUPPORT

![](_page_29_Picture_1.jpeg)

ENABUNG TECHNOLOGIES

![](_page_29_Picture_2.jpeg)

![](_page_30_Picture_0.jpeg)

![](_page_31_Picture_0.jpeg)

![](_page_31_Picture_1.jpeg)

Field of 3D deformations of a spongy bone cube in compression

![](_page_31_Picture_3.jpeg)

![](_page_32_Picture_0.jpeg)

ENABLING TECHNOLOGIES

Importance of modeling in the process of development of biomedical implants

# **OTHER EXAMPLES**

![](_page_32_Picture_4.jpeg)

![](_page_33_Picture_0.jpeg)

#### TOTAL DISC REPLACEMENT

**Total Disc Replacement** 

# Understand the effect of the TDR on the physiologic motion behavior of the spine segment

1. Effect of disc prosthesis positioning

![](_page_34_Figure_4.jpeg)

 Effect of the disc prosthesis on adjacent levels – Comparison with a rigid posterior fixation device LING TECHNOLOG

![](_page_34_Figure_6.jpeg)

![](_page_35_Figure_0.jpeg)

![](_page_36_Figure_0.jpeg)

ENNRUNG TECHNOLOGIES

![](_page_36_Picture_1.jpeg)

![](_page_37_Figure_0.jpeg)

![](_page_37_Figure_1.jpeg)

![](_page_38_Picture_0.jpeg)

![](_page_38_Picture_1.jpeg)

#### THERAPY STRATEGIES & SURGICAL TECHNIQUES

# SURGICAL TECHNIQUES

![](_page_38_Picture_4.jpeg)

# **Therapy Strategy**

 Pedicle Screw Placement Strategy

SERVICES & SUPPORT

![](_page_39_Picture_2.jpeg)

Hedtronic

Philippe Maxy, Medtronic Lawrence G. Lenke, MD, St. Louis, MO Timothy R. Kuklo, MD, Washington, DC David W. Polly, Jr., MD, Washington, DC Michael F. O'Brien, MD, Denver, CO

INTEGRATED SPINE SOLUTIONS

![](_page_39_Figure_5.jpeg)

![](_page_39_Figure_6.jpeg)

# EXPERIMENTAL TESTS

Angle of Kyphosis

![](_page_39_Picture_9.jpeg)

ENABUNG TECHNOLOGIES

Forces & Moments In The Construct

FEA Main Rotation in Flexion

![](_page_40_Picture_0.jpeg)

## **Surgical Technique Evaluation**

#### VCM Surgical Technique Modelization

![](_page_40_Picture_3.jpeg)

SERVICES & SUPPORT

![](_page_40_Picture_4.jpeg)

ENABLING TECHNOLOGIES

INTEGRATED SPINE SOLUTIONS

![](_page_41_Picture_0.jpeg)

![](_page_42_Picture_0.jpeg)

INTEGRATED

# Surgical Technique Evaluation

Pedicle Subtraction Osteotomies

![](_page_42_Figure_4.jpeg)

SERVICES & SUPPORT

![](_page_42_Picture_5.jpeg)

![](_page_43_Figure_0.jpeg)

- Screw shaft / rod angle for Mono (a) and Poly-axial (b) constructs.
- Rod contour for Mono (c) and Poly-axial (d) constructs

SERVICES & SUPPORT

INTEGRATED SPINE SOLUTIONS

![](_page_44_Figure_0.jpeg)

INTEGRATED SERVICES & SUPPORT

![](_page_45_Picture_0.jpeg)

![](_page_46_Figure_0.jpeg)

![](_page_47_Figure_0.jpeg)

![](_page_48_Figure_0.jpeg)

![](_page_49_Picture_0.jpeg)

![](_page_50_Picture_0.jpeg)

THEOREM

#### SPIDER FIXATION SYSTEM

![](_page_51_Figure_2.jpeg)

![](_page_51_Picture_3.jpeg)

![](_page_51_Picture_4.jpeg)

![](_page_51_Picture_5.jpeg)

![](_page_51_Picture_6.jpeg)

![](_page_52_Picture_0.jpeg)

#### SPIDER FIXATION SYSTEM

#### **Design Optimization**

ENNBUNG TECHNOLOGIES

![](_page_52_Figure_3.jpeg)

![](_page_52_Figure_4.jpeg)

![](_page_53_Picture_0.jpeg)

ENABLING TECHNOLOGIES

#### **Other Numerical Models**

#### **Rigid Block Analysis**

![](_page_54_Figure_2.jpeg)

![](_page_54_Figure_3.jpeg)

# « True » corrective forces concept

C.E. Aubin, X. Wang, D. Crandall, S. Parent, H. Labelle

![](_page_55_Picture_3.jpeg)

#### IMAST

11. Biomechanical Effectiveness of Three Types of Pedicle Screws for the Spinal Instrumentation of Adolescent Idiopathic Scoliosis

Xiaoyu Wang, PhD; Carl-Eric Aubin, PhD, PEng; Hubert Labelle, MD; Dennis Crandall, MD; Stefan Parent, MD, PhD

#### Spine

SPINE Volume xx, Number ©2012, Lippincott Williams

**BIOMECHANICS** 

Biomechanical Analysis of Corrective Forces in Spinal Instrumentation for Scoliosis Treatment

Xiaoyu Wang, PhD,\* Carl-Eric Aubin, PhD, PEng,\*+ Hubert Labelle, MD,+ Stefan Parent, MD, PhD,+ and Dennis Crandall, MD,‡

![](_page_55_Picture_12.jpeg)

![](_page_55_Picture_13.jpeg)

FAS

![](_page_55_Picture_14.jpeg)

![](_page_55_Picture_15.jpeg)

Dorso-axial

![](_page_55_Picture_18.jpeg)

![](_page_55_Picture_19.jpeg)

![](_page_55_Picture_20.jpeg)

![](_page_55_Picture_21.jpeg)

ENABUNG TECHNOLOGIES

INTEGRATED

SPINE SOLUTIONS

LOWEST forces

![](_page_55_Picture_23.jpeg)

![](_page_55_Picture_24.jpeg)

![](_page_55_Picture_25.jpeg)

![](_page_56_Picture_0.jpeg)

ROT: 0

SERVICES & SUPPORT

INTEGRATED

SPINE SOLUTIONS

![](_page_56_Picture_1.jpeg)

![](_page_56_Picture_2.jpeg)

57

![](_page_57_Picture_0.jpeg)

**Numerical Simulations** 

SERVICES & SUPPORT

![](_page_57_Picture_2.jpeg)

INTEGRATED SPINE SOLUTIONS

58

![](_page_58_Figure_0.jpeg)

And Tomorrow...

# Personalized 3D Reconstruction

![](_page_59_Figure_3.jpeg)

# And Tomorrow...

## Spine Surgery Simulator

Personalized Biomechanical Model

SERVICES & SUPPORT

• Patient's spine stiffness estimated from side bending radiographs

Computer Methods in Biomechanics and Biomedical Engineering 2003. Vot. 6 (1), pp. 27–32 Biomechanical Modeling of Posterior Instrumentation of the Scolibitic Spine

Medical & Biological Engineering & Computing 2004, Vol. 42 Patient-specific mechanical properties of a flexible multi-body model of the scoliotic spine

Y. Petit<sup>1,2</sup> C.-É. Aubin<sup>1,2</sup> H. Labelle<sup>2</sup>

INTEGRATED

SPINE SOLUTIONS

![](_page_60_Picture_8.jpeg)

![](_page_60_Picture_9.jpeg)

ENABUNG TECHNOLOGIES

![](_page_61_Picture_0.jpeg)

# And Tomorrow...

# Spine Surgery Simulator

![](_page_62_Figure_3.jpeg)

Preoperative Planning Simulator for Spinal Deformity Surgeries

C. E. Aubin, PhD,\*t H. Labelle, MD,t C. Chevrefils, MASc,\*t G. Desroches, MASc,\*t J. Clin, MASc,\*t and A. Boivin M. Eng\*t

INTEGRATED SPINE SOLUTIONS

![](_page_62_Picture_8.jpeg)

![](_page_62_Picture_9.jpeg)

![](_page_62_Picture_10.jpeg)

![](_page_62_Picture_11.jpeg)

63

ENABLING TECHNOLOGIES

![](_page_63_Picture_0.jpeg)

#### Medtronic

# And Tomorrow...

# Patient Pozitioning System

#### Per-Op Simulations

![](_page_64_Picture_4.jpeg)

- Maintain patient (stability), minimize • bleeding, minimize chance of damage to vital structures, allow proper ventilation, avoid post-operative morbidity
- Facilitation of instrumentation, • procedures (laminectomy, discectomy, decompression), imaging
- Optimize patient positioning (intra-op • motion), multifunctional, preservation of natural biomechanics

SERVICES & SUPPORT

INTEGRATED SPINE SOLUTIONS

![](_page_64_Picture_9.jpeg)

Lower Limb Pozitioning

![](_page_64_Picture_10.jpeg)

![](_page_64_Picture_11.jpeg)

![](_page_64_Picture_12.jpeg)

![](_page_64_Picture_13.jpeg)

![](_page_64_Picture_14.jpeg)

![](_page_64_Picture_15.jpeg)

Real Time Pressure Monitoring

![](_page_64_Picture_16.jpeg)

![](_page_64_Picture_17.jpeg)

And Tomorrow...

# Virtual Reality Surgery Simulators

Implant Insertion

![](_page_65_Picture_4.jpeg)

![](_page_65_Picture_5.jpeg)

![](_page_65_Picture_6.jpeg)

![](_page_65_Picture_8.jpeg)

After Multiple Implant Insertions

#### Rod Manipulation / Biomechanical Simulations

![](_page_65_Picture_11.jpeg)

![](_page_65_Picture_12.jpeg)

![](_page_65_Picture_13.jpeg)

![](_page_65_Picture_14.jpeg)

![](_page_66_Picture_0.jpeg)

"By using FEA, Medtronic is able to assess the nature of stresses on spinal structures – information that is crucial to designing implants or other devices to treat spinal damages."

![](_page_66_Picture_2.jpeg)

![](_page_66_Picture_3.jpeg)

![](_page_67_Picture_0.jpeg)

![](_page_67_Picture_1.jpeg)

![](_page_67_Picture_2.jpeg)

#### Philippe MAXY Principal Scientist Route du Molliau CH1131 Tolochenaz SWITZERLAND Philippe.maxy@medtronic.com

Philippe MAXY

in

![](_page_67_Picture_4.jpeg)